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Navigation: Theory, Algorithm And Implementation By
Jingchun Yin**

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Autonomous Robots and Agents, 2009. ICARA 2009. 4th International Conference on

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is introduced for multi-robot localization and M. Yin, F. Lian, Robot localization and mapping by matching the a weighted clustering algorithm for mobile

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1. Introduction. Recent years have seen great improvements of simultaneous localization and mapping (SLAM), which serves as the core of a large amount of robotic

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Distributed intelligent assistance robotic system

for path planning and localization of mobile of the mobile robot. This algorithm effectively of Intelligent and Robotic Systems: Theory

Simultaneous localization and mapping - wikipedia,

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Abstract: This paper addresses the problem of Simultaneous Localization and Mapping (SLAM) when working in very large environments. A Hybrid architecture is presented

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Meshslam: robust localization and large-scale

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